# 3D Laser Imaging for Pavement Survey at 60 mph and True 1mm Resolution

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#### First Gen Vehicle's Exterior







#### Telescoped Camera and Four Strobe Lights







#### **Second Generation DHDV**





## **Common Problems**

Poor Distress Field Data

- Particularly Cracking
- Operating 3D Profile Line Rate
  - From 4000, 6000, to 8000/sec
  - About 4mm to 6mm (¼-inch) Resolution in the Longitudinal Direction at 60MPH (100KM/H)
  - Good Enough for Some Purposes; Not Sufficient





# **PaveVision3D Ultra Approach**

- Use Multiple Sensors
- Increase 3D Profile Line Rate to 30,000/second
- Complete Coverage of Pavement Lane
  - True 1mm at Any Data Collection Speed up to 60MPH (100KM/H)





### **Data Rate & Power at 60MPH**

#### Single Computer Data Rate for 3D Only 4000x2x28000=224,000,000 bytes, 224 MB/sec before compression Continuous for a few hours non-stop Advantage Low Power < 1000 watts in all</p> Complete Coverage at True 1mm 9

## **Data Compression & Management**

### Raw Data from All Sensors

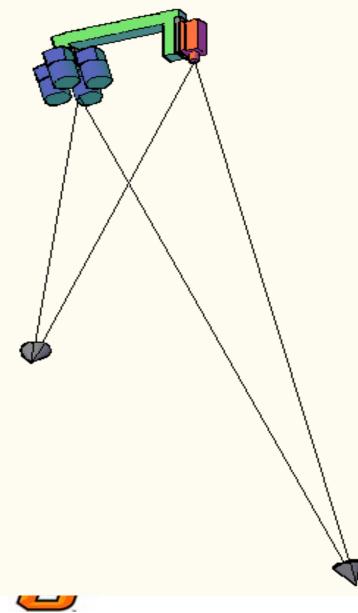
- Over 10GB per Mile at 60MPH (100KM/H)
- 2D Compression: JPG/JPG20003D Compression

 Proprietary Compression: over 10:1
 Production Data to Computer Storage: 1GB per Mile
 Relational Database Driven





## **PaveVision3D Ultra Design**



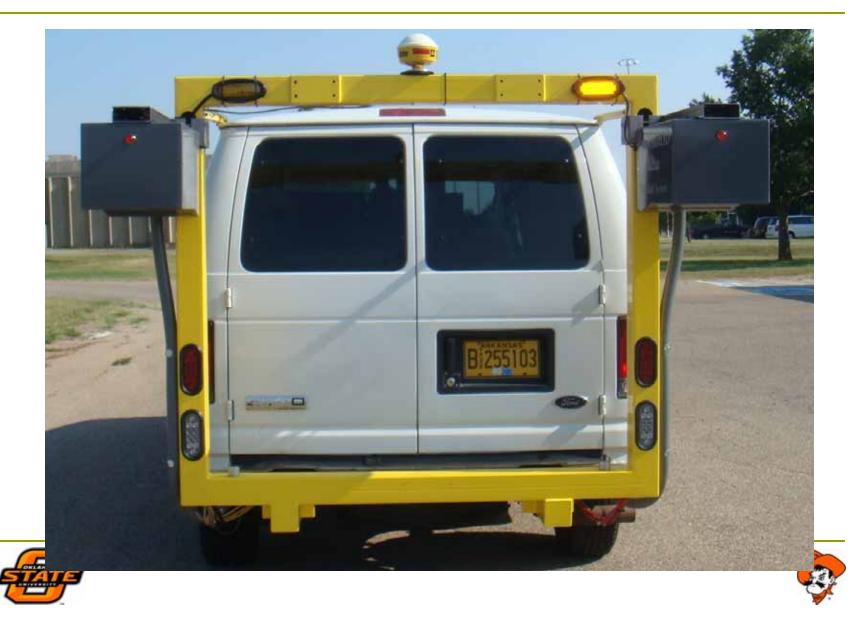




#### **PaveVision3D Ultra**



#### **PaveVision3D Ultra**



### **PaveVision3D Ultra**



### **Virtual Pavement**

Imm Pavement Surface in All Three Dimensions High-Precision IMU Grades Horizontal Curves Cross-Slope





# **PaveVision3D Ultra Applications**

Now

- Cracking, Rutting, IRI, Macro-Texture (MPD, MTD)
- Safety Analysis: High-Friction, Rumble Strips, Hydroplaning/Grooving
- Virtual Surface for Visualization
- In Progress
  - Longitudinal Profiling
  - Comprehensive Evaluation of Distresses
    - Comprehensive Performance Metric





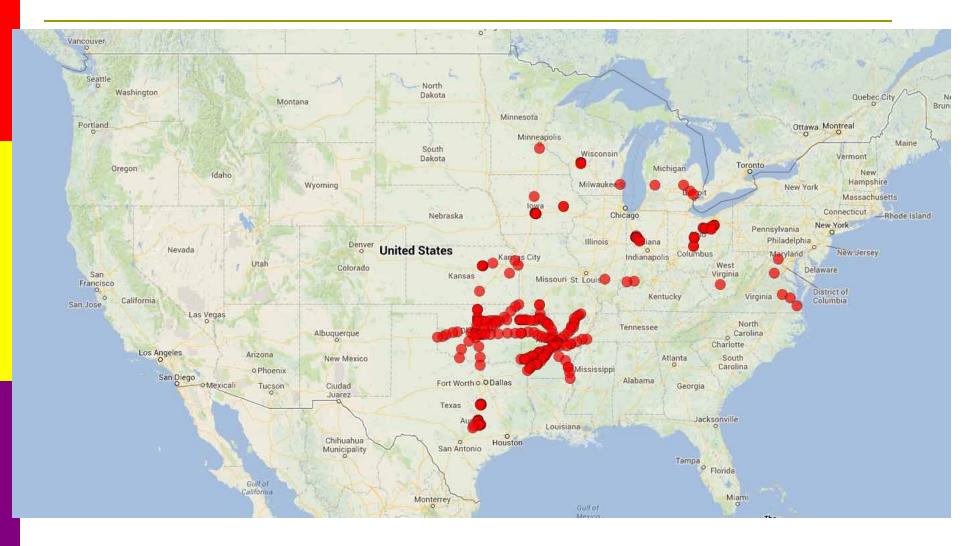
# **Example Projects/Applications**

- Arkansas Highway Network
- Oklahoma Interstate Network
  INDOT
- TxDOT Project 6663 Phase II
- Ohio DOT
- LTPP Sites, Including Those with WIM
- High Friction Surface
- Next Generation Concrete Surface (NGCS)





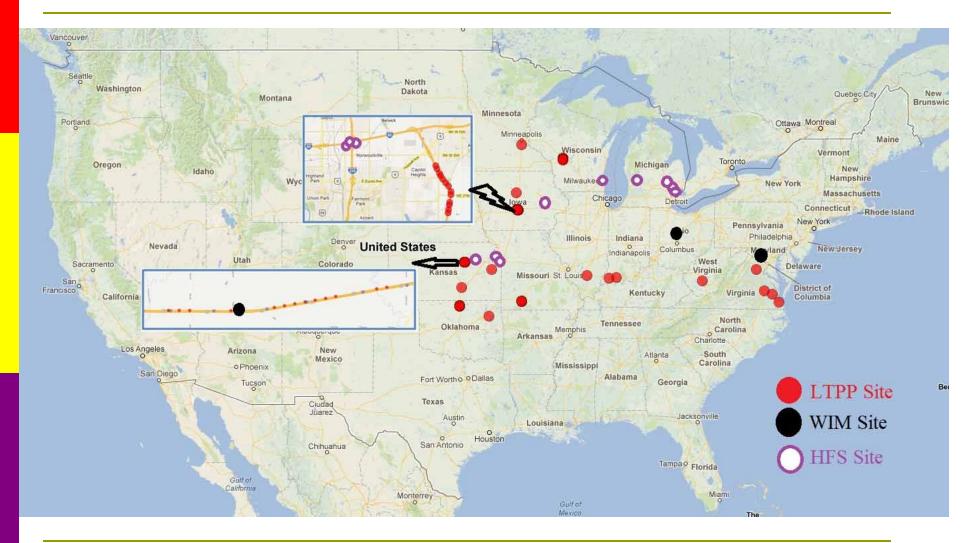
## **Example Projects/Applications**







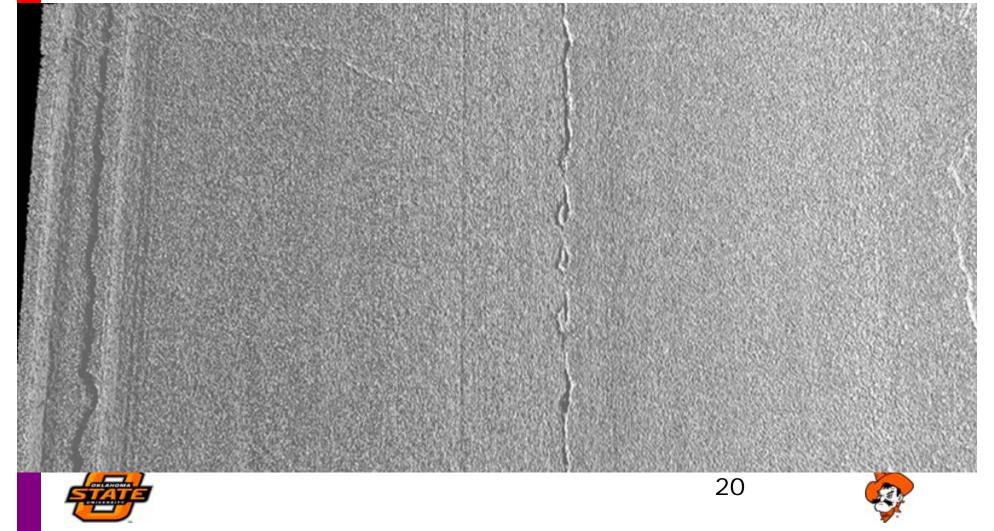
## **LTPP Data Collection**



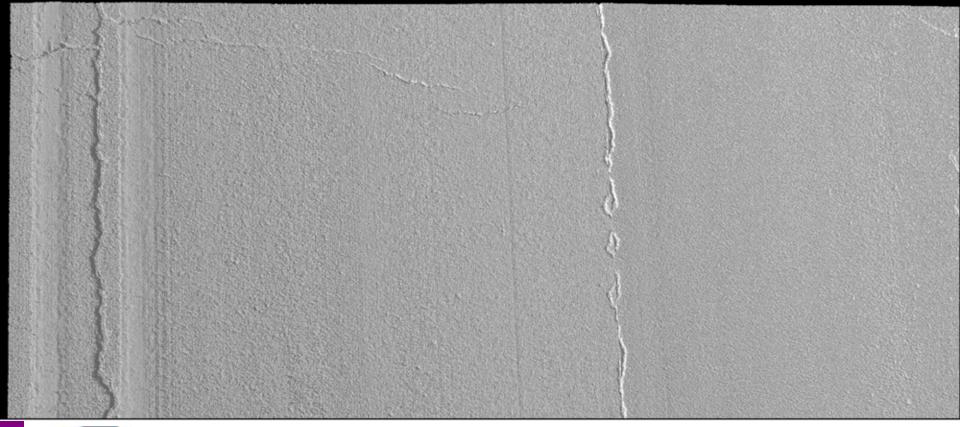




# **Comparison on the Same Pavement D**7000 3D Profiles/Sec

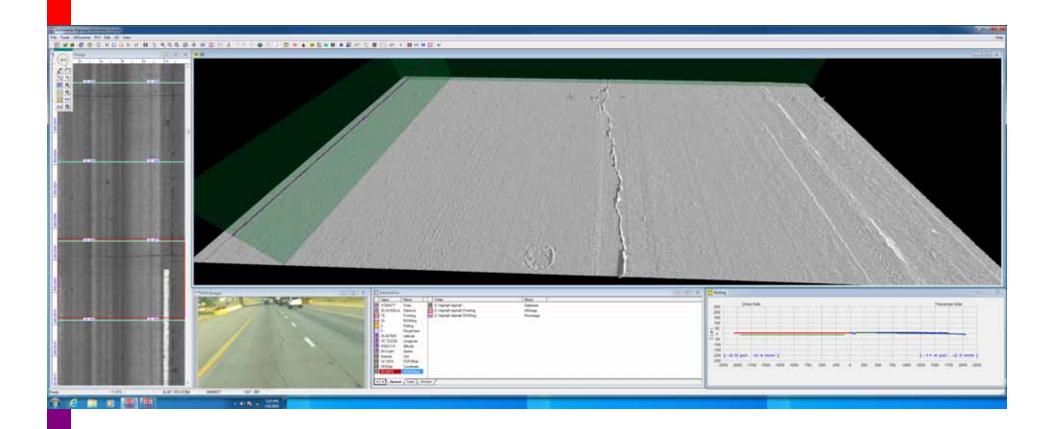


# **Comparison on the Same Pavement** 28,000 3D Profiles/Sec



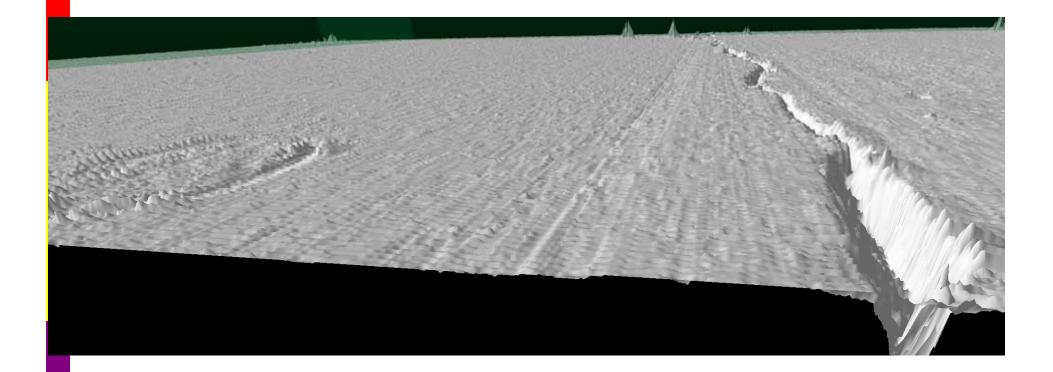






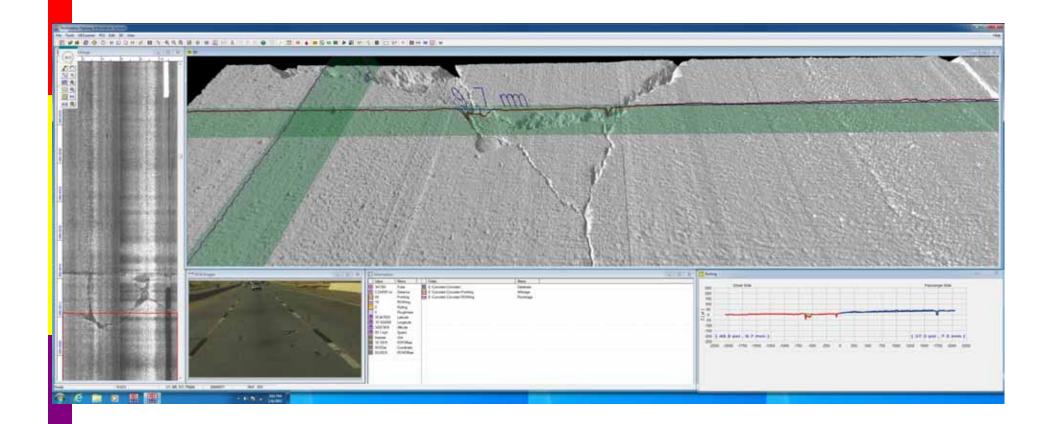






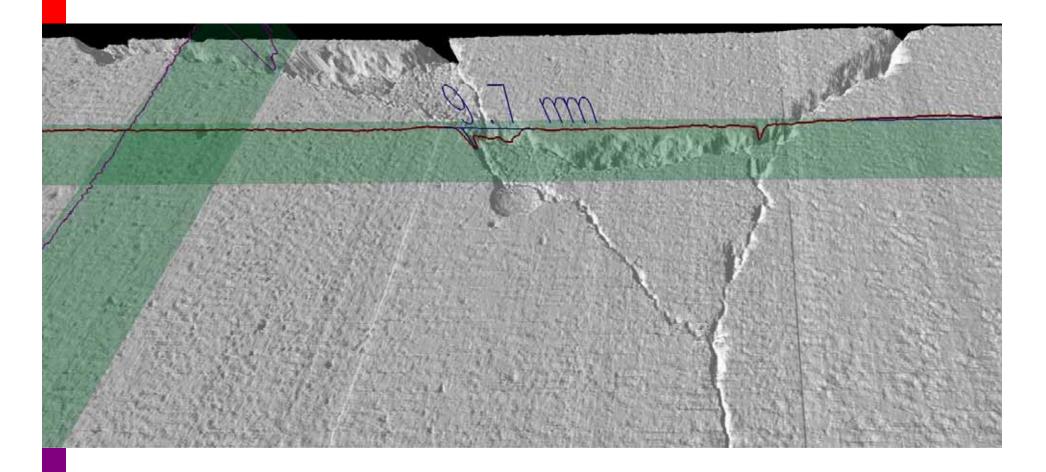






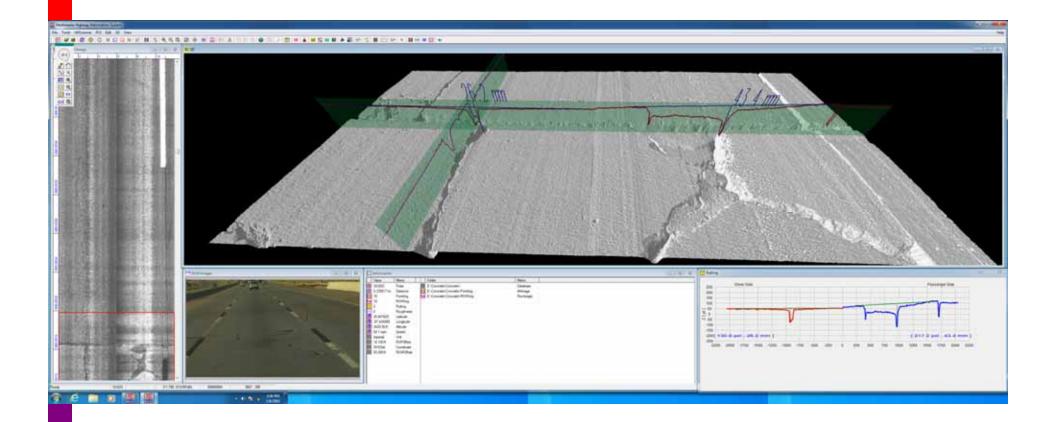






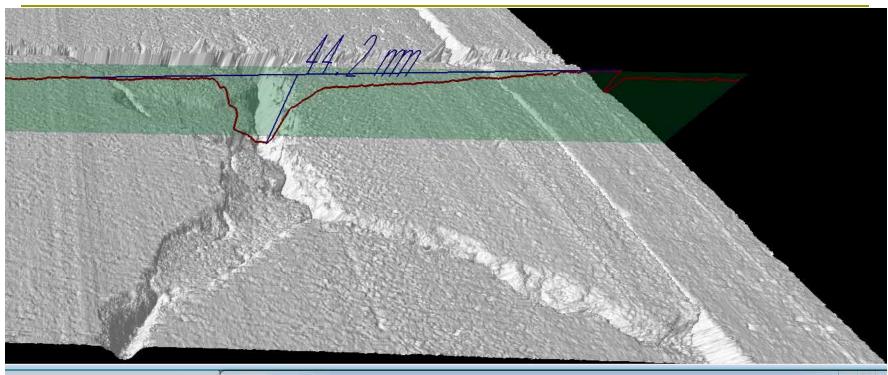




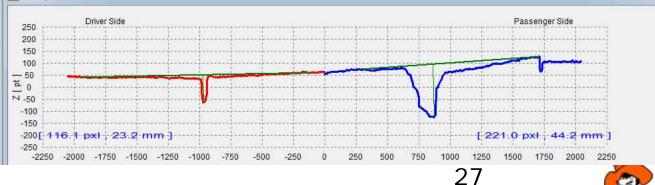






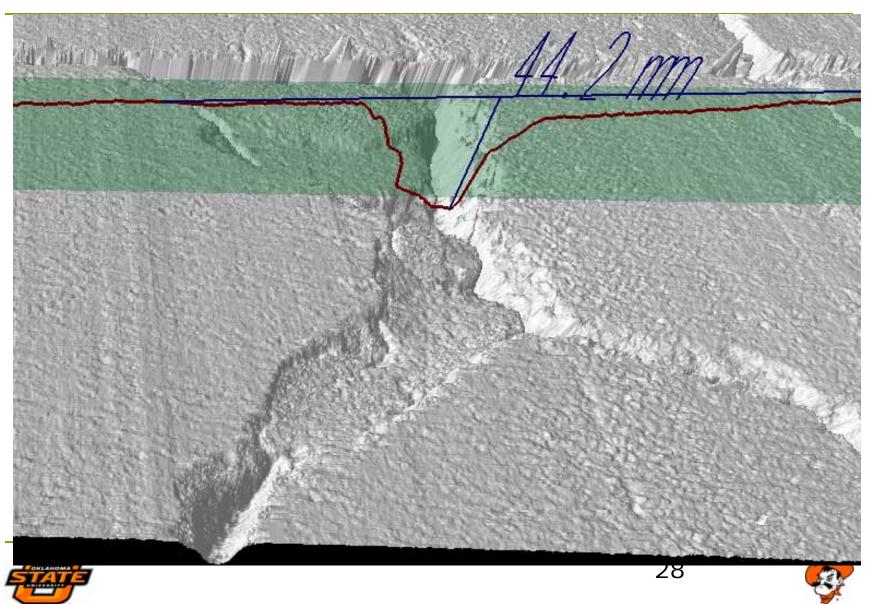


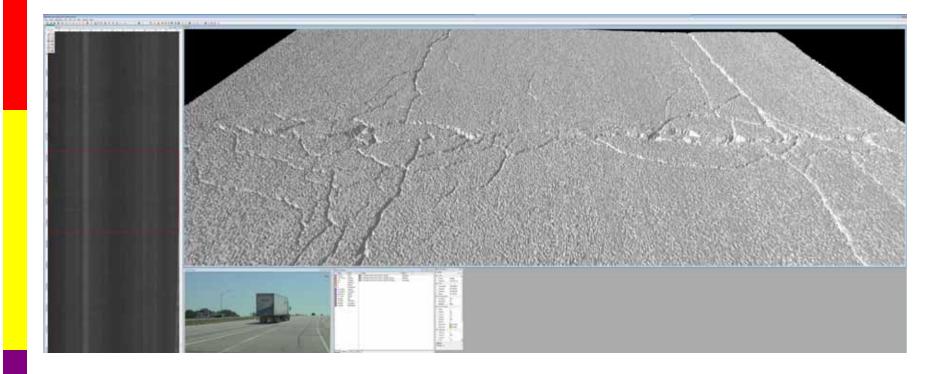
😑 🗉 🔀 🞽 Rutting





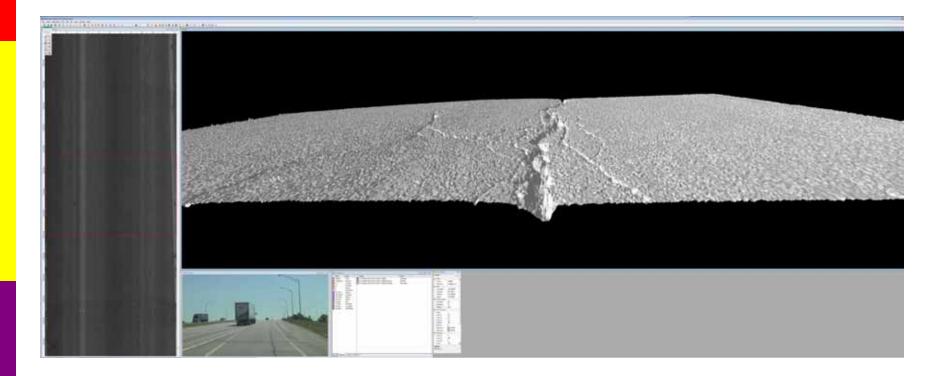






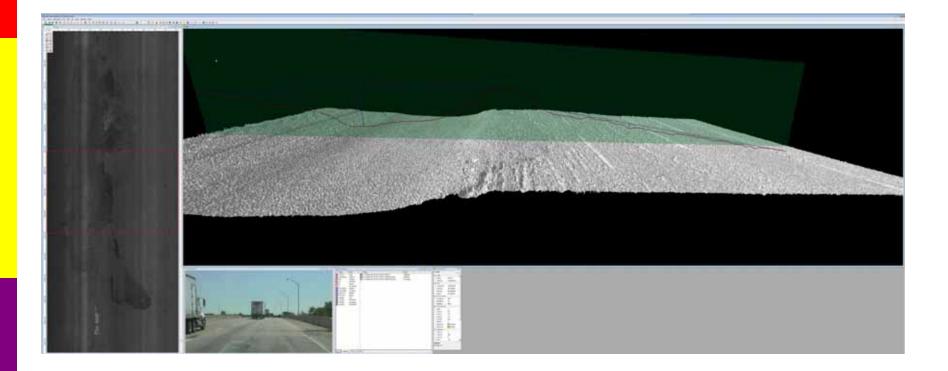






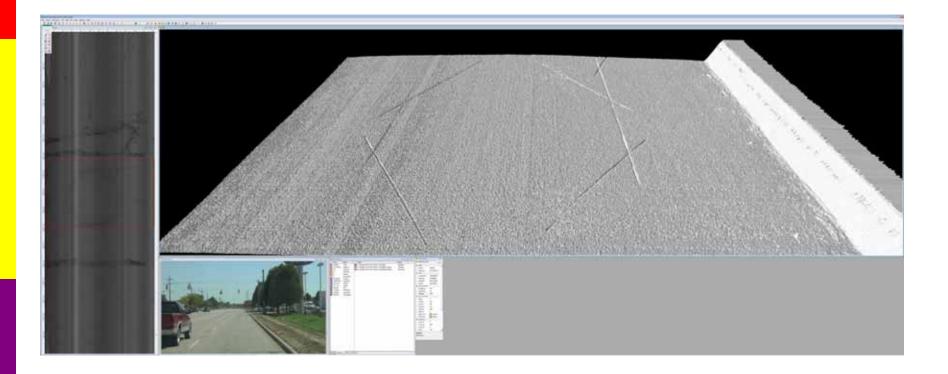






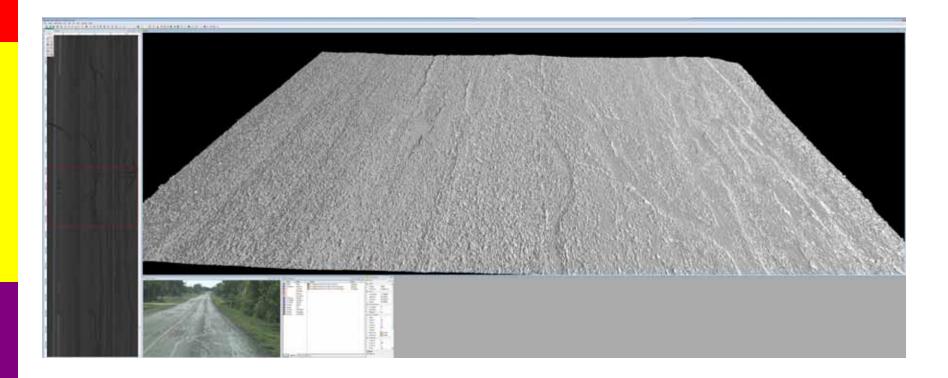












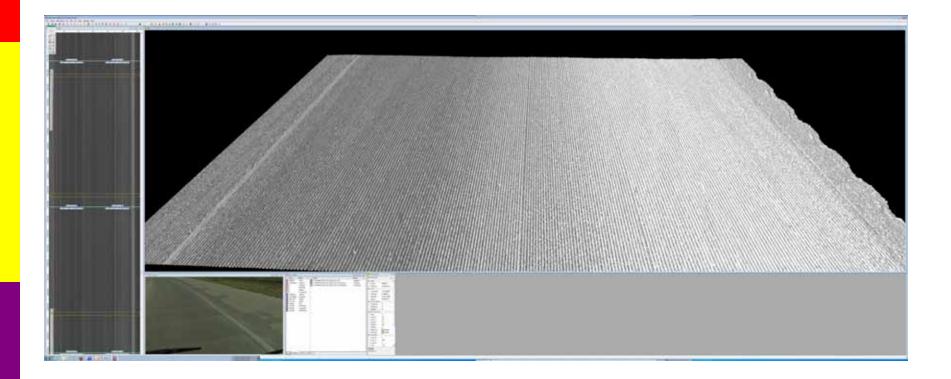






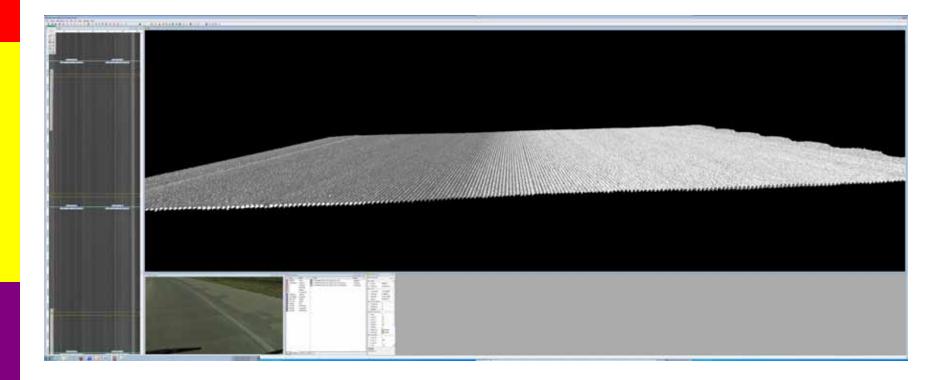






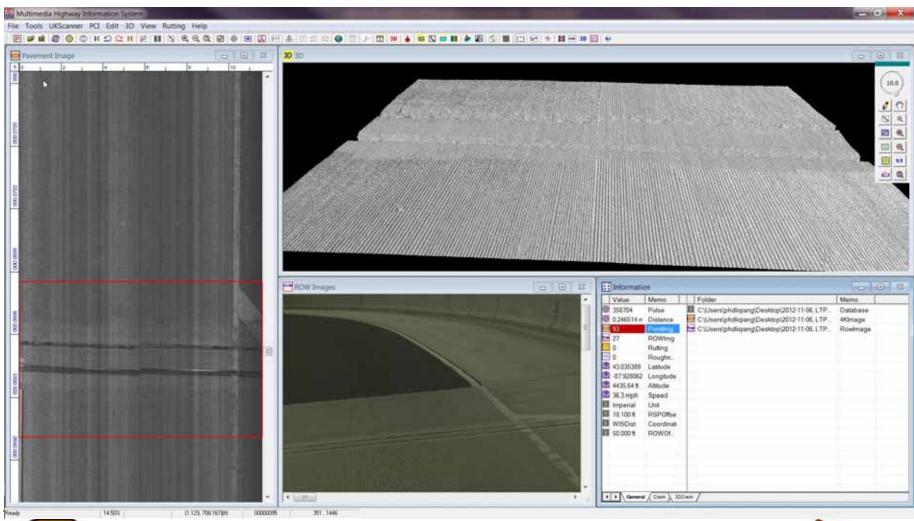






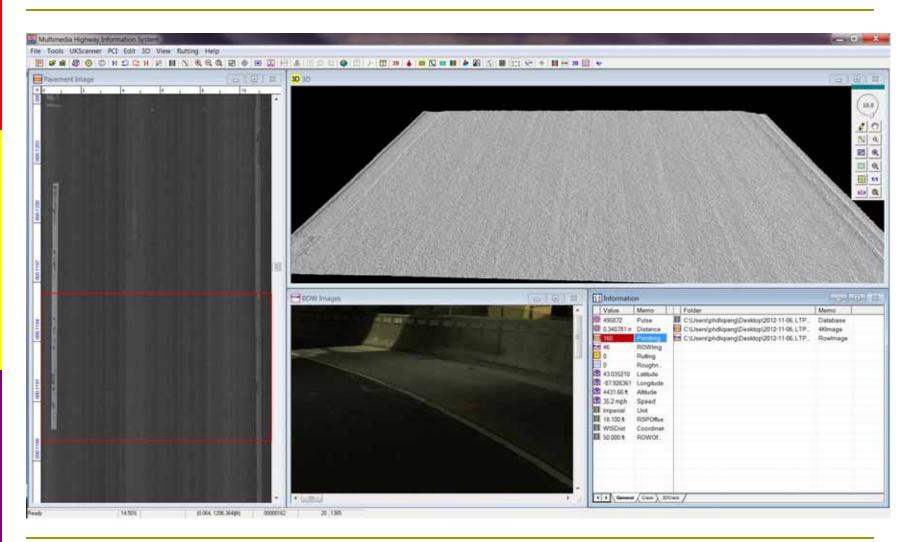








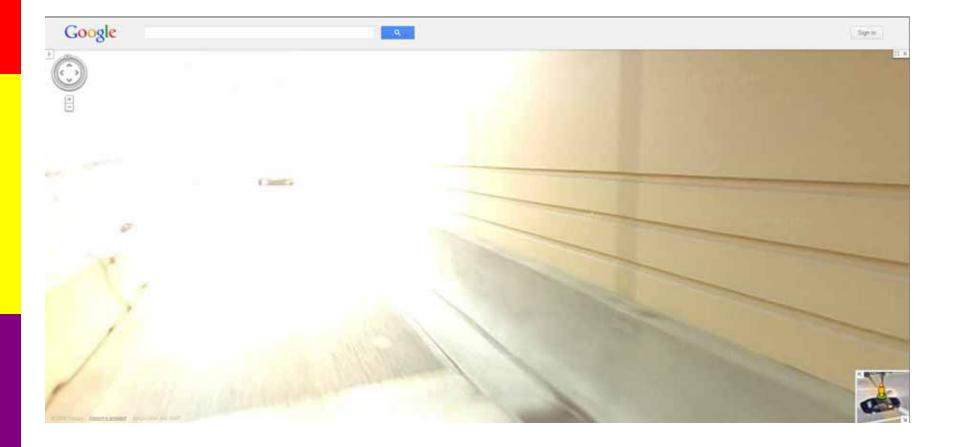








## **Google Image at the Same HFS**



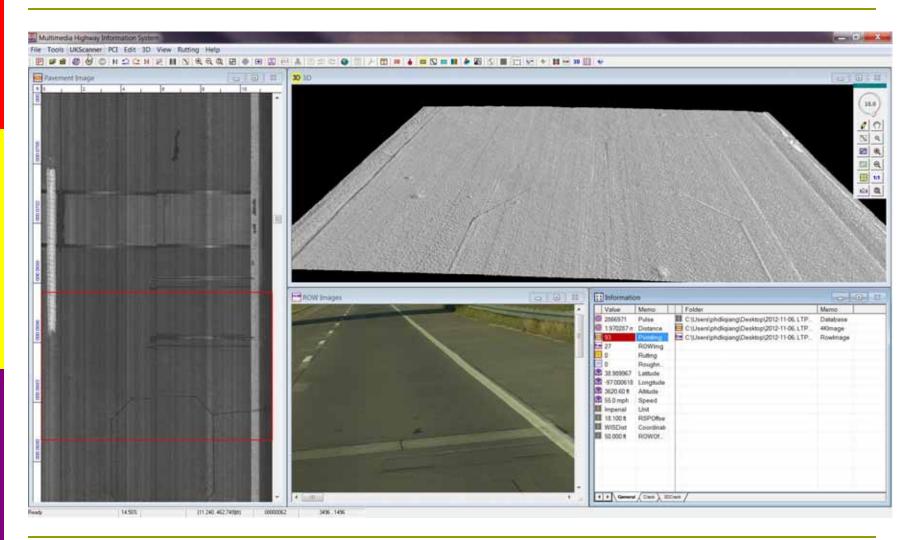




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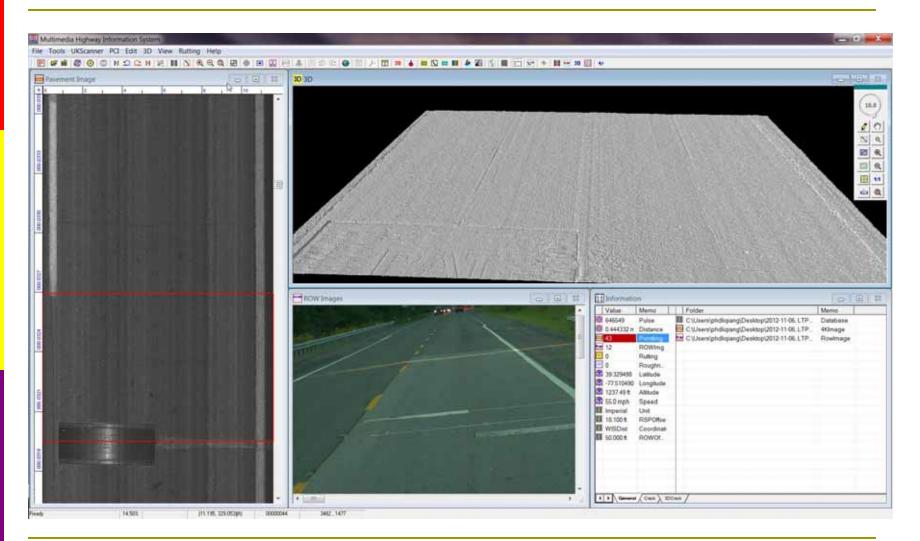






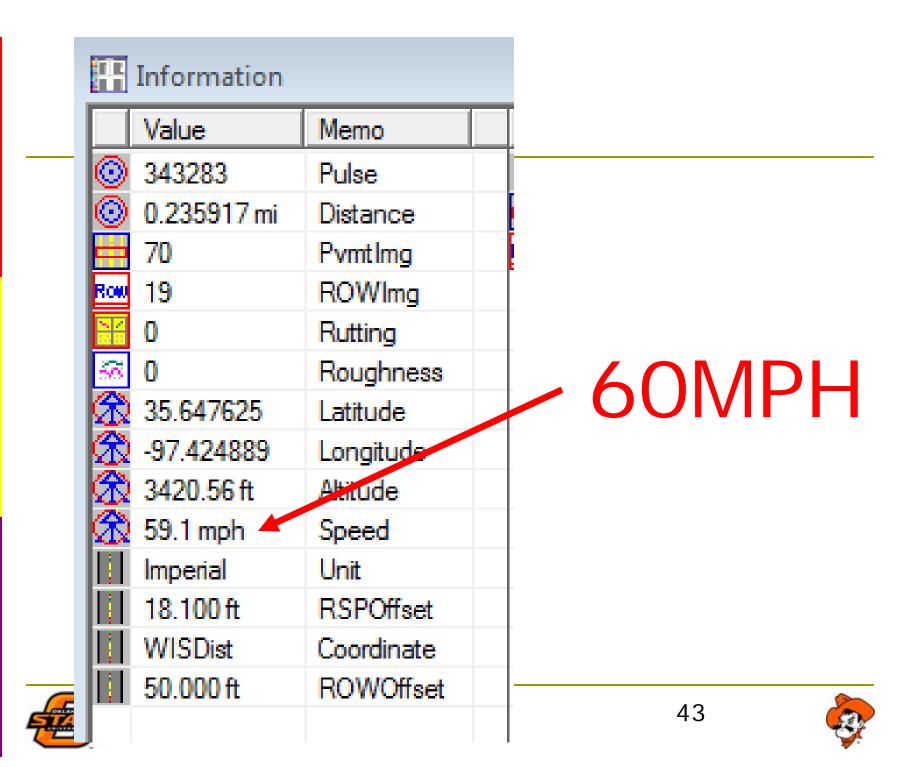




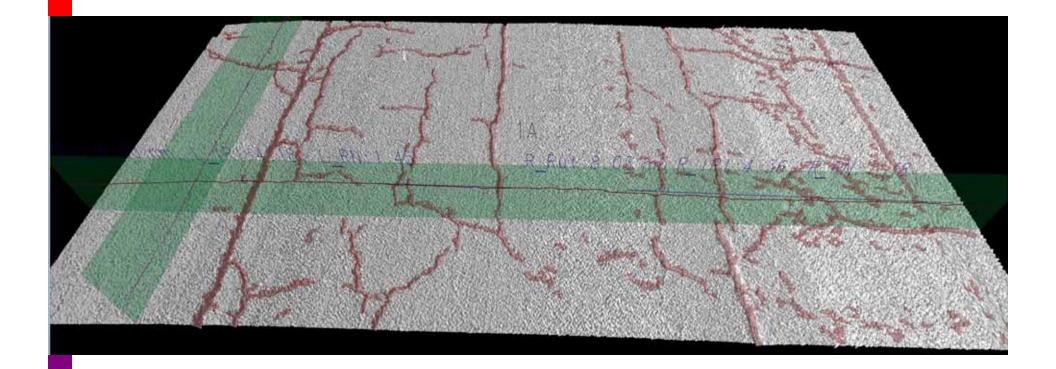








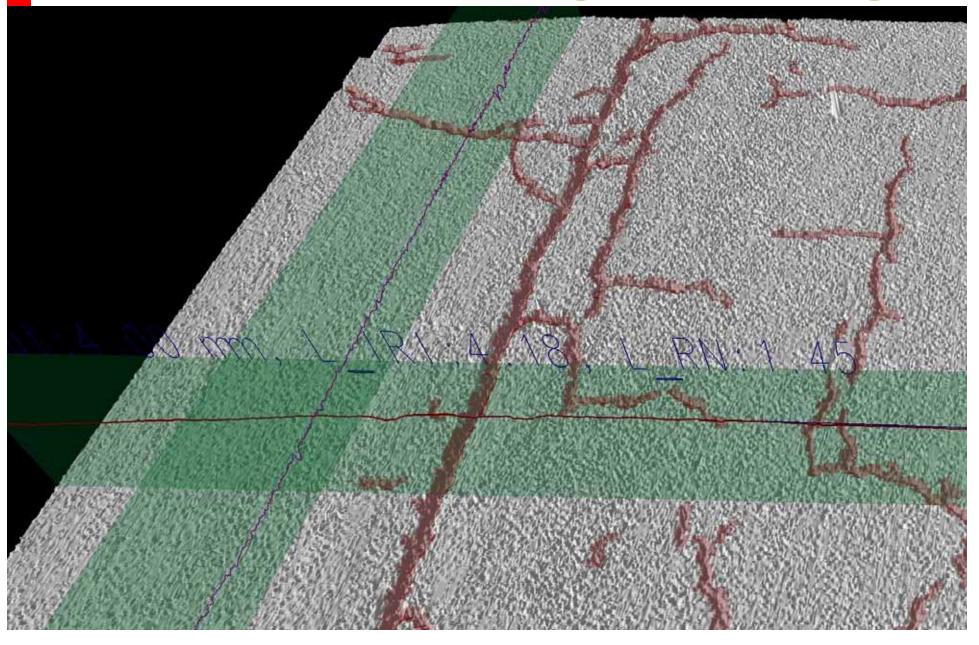
# **Cracking & Profiling**







### Zoomed-In, Cracking & Profiling



### **Evaluation of PaveVision3D Ultra**

- Comparisons of Pavement Surface Texture Measurements with LS-40 Surface Analyzer
- Surface Drainage Evaluation Using IMU and 1mm 3D Texture Data
- Automated Groove Identification and Measurement
- Evaluation of Pavement Transverse Deformation Based on AASHTO PP69-10

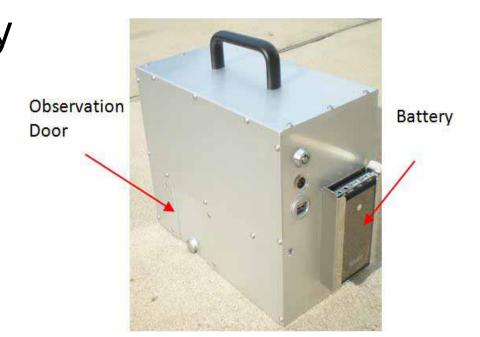




### **LS-40 Pavement Surface Analyzer**

Scanned Area:

- 4.5" long by 4" wide
- Data Pixel Quantity
  2048 x2448
  Horizontal Resolution
   0.056mm







#### **LS-40 Software Interface**

		LS-40 Tex	ture Scanner	1.03					
Measurement Parameters		Texture Dat							
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Camera: Not Found! Index: (	0 Rate: 10.0	ETD: 2.52	SPH: 4.13	STD: 0.597	MIN: 0.	.00	B=0000	, R=000	
							<< H		Video Live
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## **Experimental Setup**

- 21 areas marked on pavement
  - Evenly spaced (15ft)
  - Ift long by 6 in wide
- Texture Measurements
  - Within marked area
  - LS40 MPD: static 5 runs
  - PaveVision3D MPD: two speeds, 10 runs each







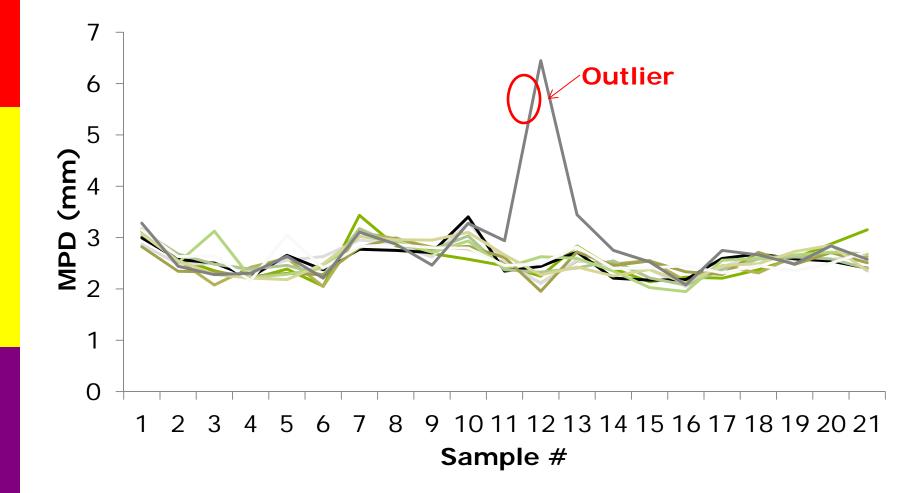
### **PaveVision3D Texture Analysis**

	s\LIN LI\Desktop\Lab Test\2 s\LIN LI\Desktop\Lab Test\2						
ieneral Info IMG Quantity: 52 Section Length: 118.872 390 ilter Mask Filter: 0 loving Average: 0	Cali.Coeff L_Cam1: 3.3137 L_Cam2: 3.2941 L_Cam3: 3.2941 L_Cam3: 3.2941 L_Cam4: 3.3529 Process	R_Cam2: 3.2156 R_Cam3: 3.196	AOI Inital IMGID: Inital Profile ID: LeftTop.x: LeftTop.y: AOI Height: AOI Width:	5  1089  1673  1089  280  160			
SAMP_ID Av	MPD Max_MPD	Min_MPD	STD	Comment			





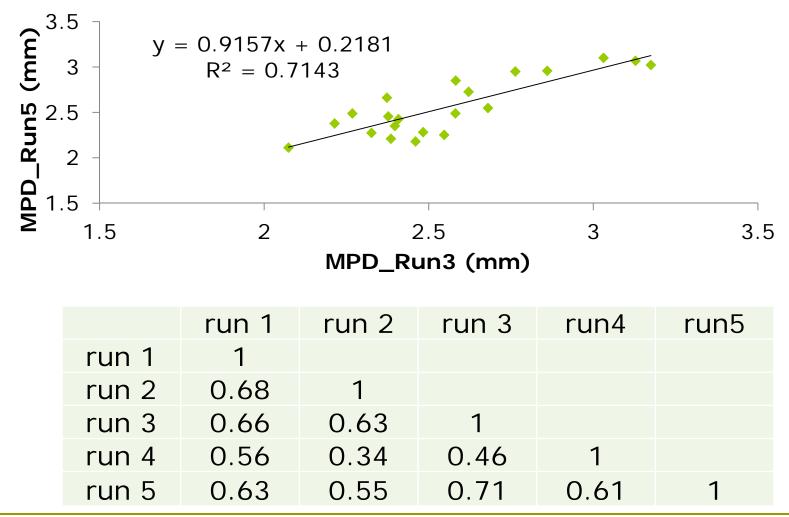
### PaveVision3D MPD (7mph)







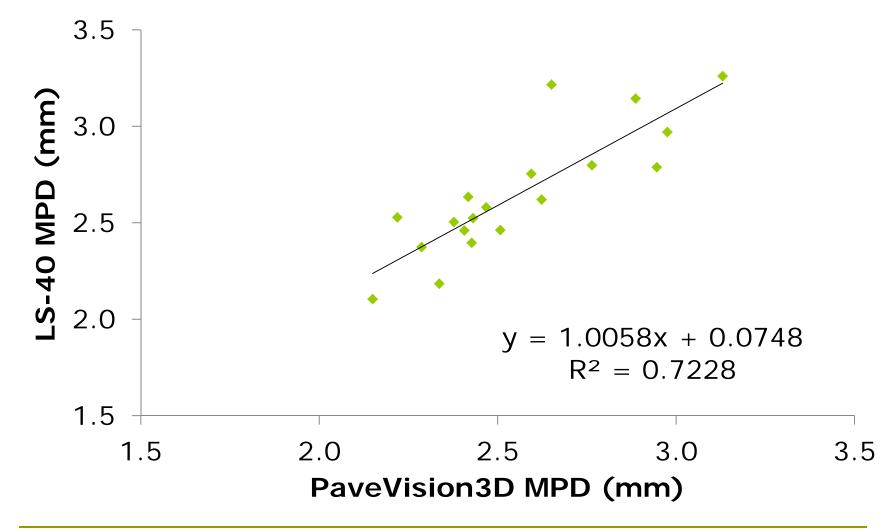
### **Correlation Analysis(7mph)**







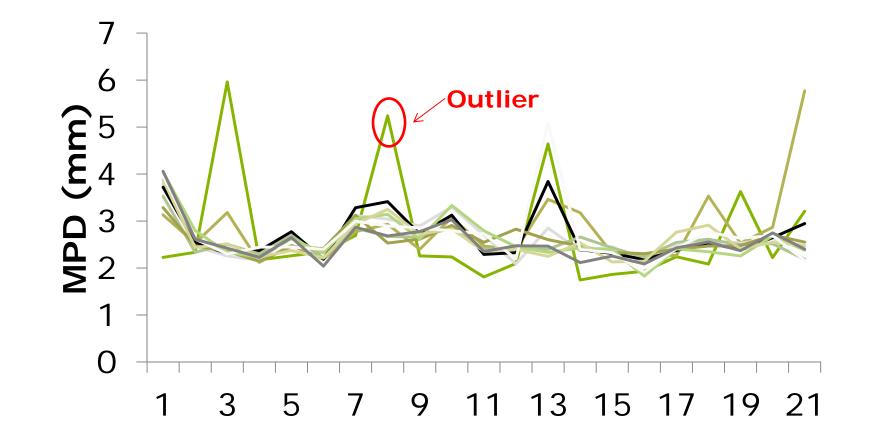
## **Comparison Analysis (7mph)**







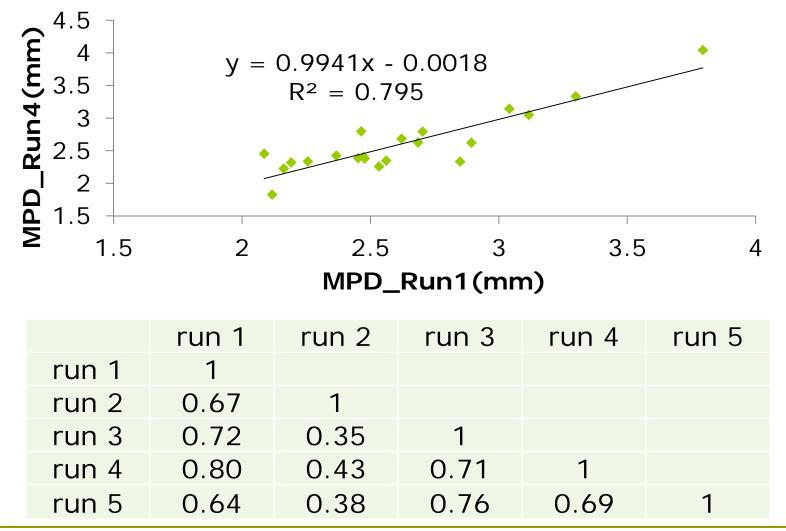
### **PaveVision3D MPD (15mph)**







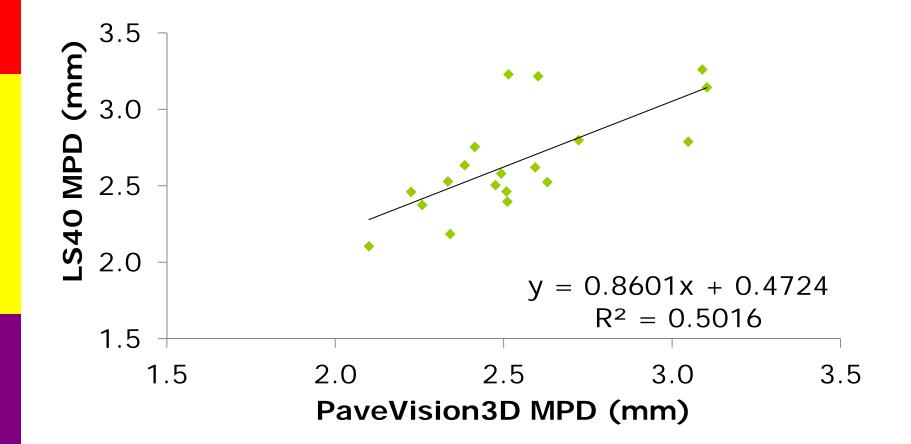
## **Correlation Analysis (15mph)**







### **Comparison Analysis (15mph)**







### **Drainage Evaluation**

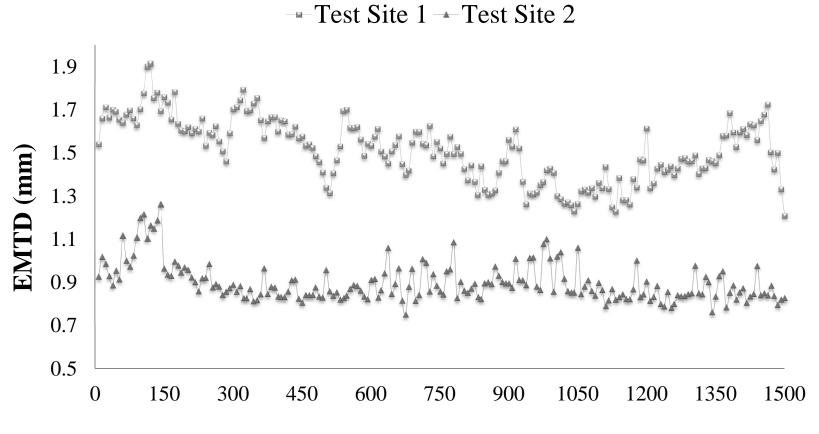
Inertial Measurement Unit (IMU)

- Consisting of accelerometers and fiberoptic gyroscopes
- Collecting positioning, cross slope and vertical slope data
- PaveVision3D Texture Data
- Hydroplanning Speed Model
  - Water film depth: pavement type, cross slope, vertical grade, rain intensity





### **Drainage Evaluation Test Results**



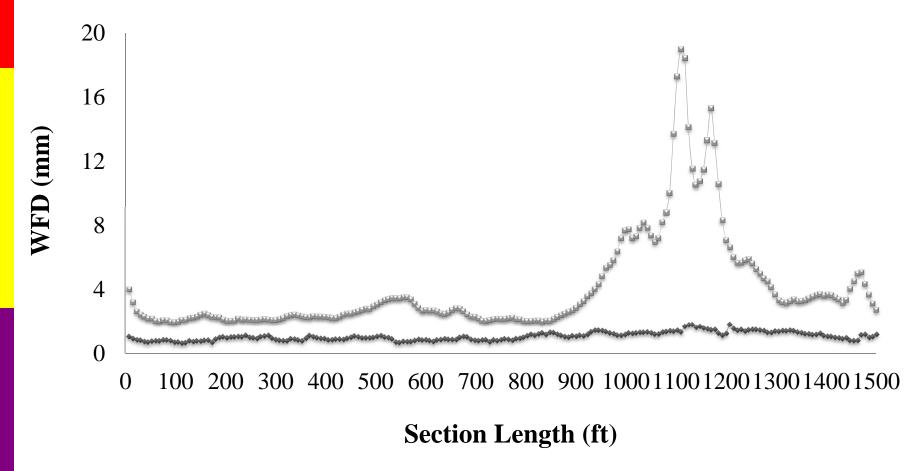
Section Length (ft)





#### **Drainage Evaluation Test Results**

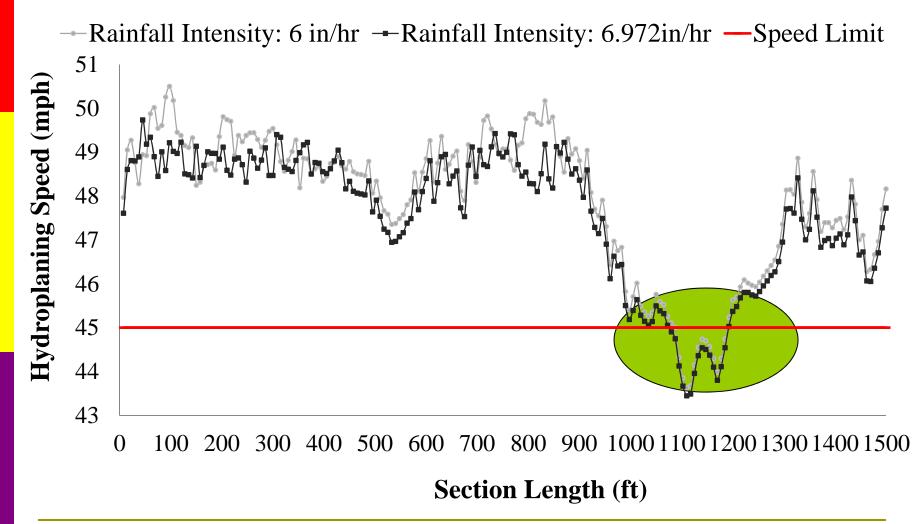
→ Test Site 1 → Test Site 2







### **Drainage Evaluation Test Results**







#### **Grooves: Airfield & Highway Pavements**

- Produces adequate skid resistance
- Prevents the occurrence of hydroplaning
- FAA Advisory Circular(AC) No. 150/5320-12C
  - Requirements for pavement groove dimension and performance
  - Needs to periodically evaluate runway groove performance
- Highway grooves
  - No standard





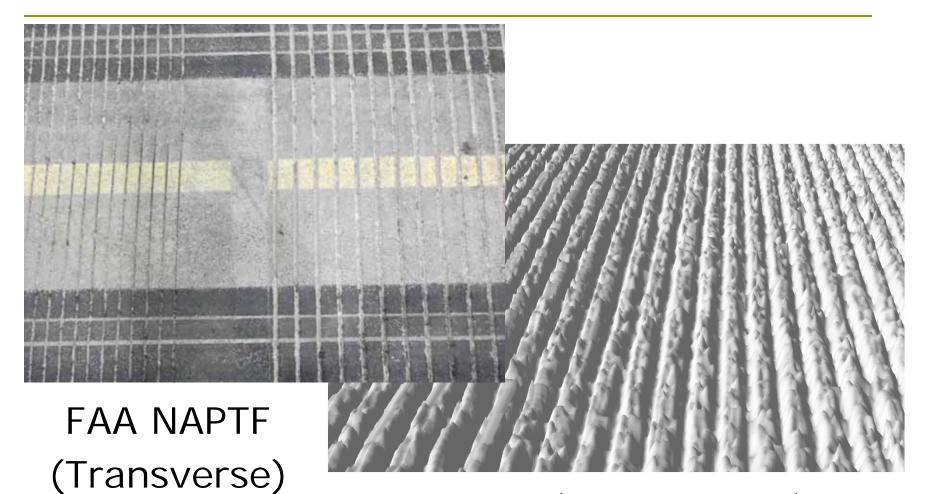
### **Groove Evaluation Approach**

- To develop an algorithm to automatically estimate groove dimensions
  - Groove Depth
  - Groove Width, and
  - Groove Spacing
- To evaluate groove performance
  - Calculated groove dimensions
  - Groove configuration, and
  - Standard groove evaluation guidelines





### Grooving

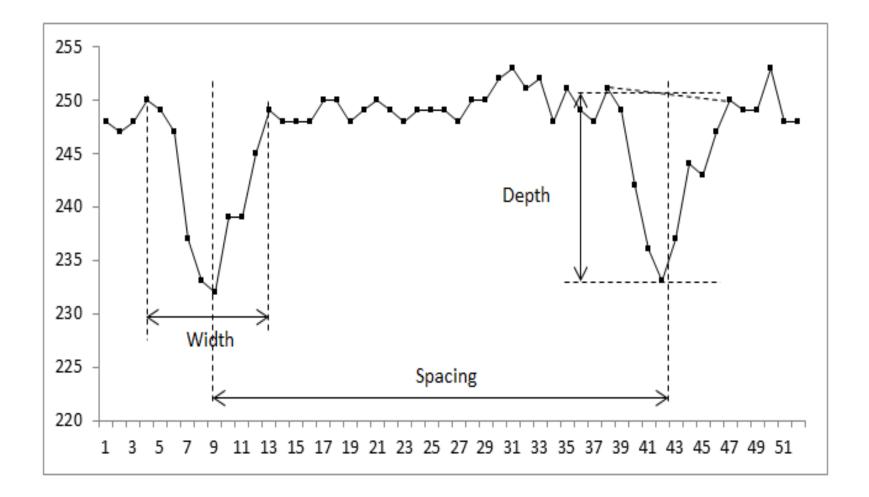


#### NGCS (Longitudinal)





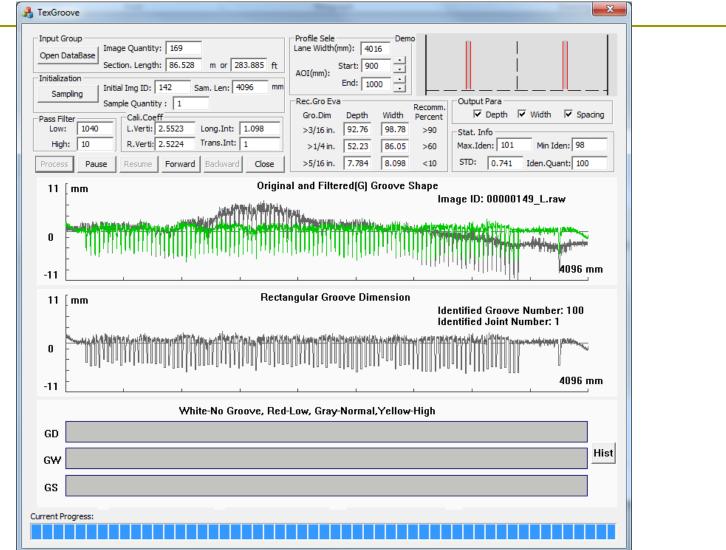
#### **Groove Dimensions**







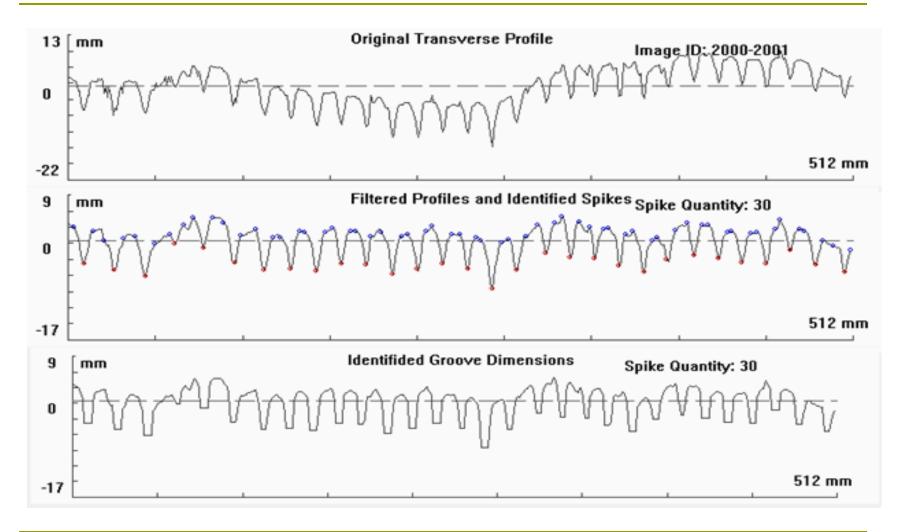
#### **Software Interface**







#### **Identification Results**







### **Evaluation of AASHTO PP69-10**

- Network Data Collection Using PaveVision3D Ultra
- Implement AASHTO PP69-10 Rutting Parameters
- Evaluate their Relationships and Propose a comprehensive Measure(s)





#### **AASHTO PP69-10 Rutting Protocol**

No.	Attribute	Acronym
1	Total Deformation Permillage	TDP
2	Left Deformation Permillage	LDP
3	<b>Right Deformation Permillage</b>	RDP
4	Left Rut Depth (mm)	LRD
5	Right Rut Depth (mm)	RRD
6	Left Rut Width (mm)	LRW
7	Right Rut Width (mm)	RRW
8	Left Rut Area (square mm)	LRA
9	Right Rut Area (square mm)	RRA
10	Total Number of Water Entrapment Points	TNW
11	Total Water Entrapment Depth (mm)	TWD
12	Total Water Entrapment Width (mm)	TWW





## **1mm Rutting Data**

#### Source

- More than 100 miles NHS in AR
  US65N and US70E
- □9000+ profiles
- Each profile 12 attributes
- Distribution of attributes
  - Slightly skewed or normally distributed





**Evaluation Methodology** Correlation Analysis Examine preliminary relations Correlation Matrix Linear Regression Analysis





### **Correlation Results**

Strong linear relations (correlation coefficient > 0.7): TDP & LDP TDP & RDP LRD & LRA RRD & RRA Weak linear relations (correlation) coefficient < 0.3)





### **Establish Quantitative Relations**

Traditional Measures Rutting depth (LRD & RRD) New Measures in PP69-10 Rutting width (LRW & RRW) Rutting area (LRA & RRA) Water related (TNW, TWD, & TWW)





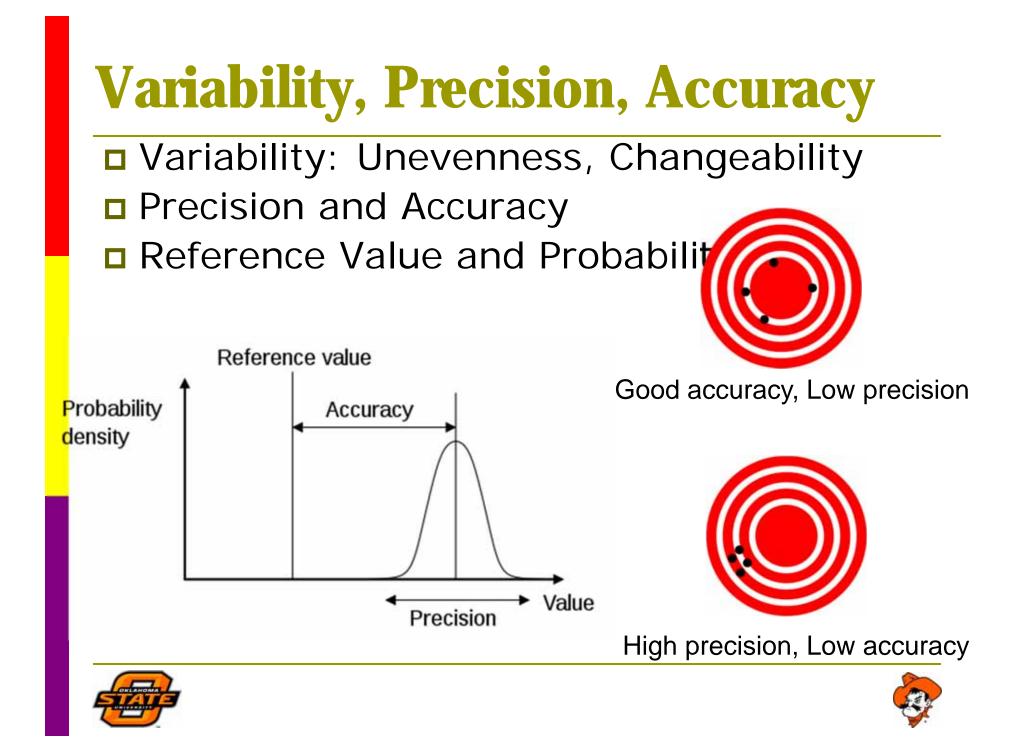
### **Regression Analysis Results**

Feasible and reliable to use rutting depth to predict rutting area measures

Other attributes: not robust to predict with rutting depth







## **Relating to Cracking Survey**

Variability & Precision Target: small variability & tight range for high precision Reference & Accuracy No good reference (Manual Survey?) Accuracy: therefore in question Probability Randomness? Accuracy: sometimes same as "bias"





### **Sources of Variability**

- Complex pavement conditions
- Varying data collection methods
- Rater inconsistencies
- Inter-rater uniformity
- Time
- Transcription, referencing and data entry
- Varying protocol & expectations





# **Conclusion Remarks**

- Sensor Technology: Completed
- Challenges to the Team & Industry: Software Solutions
  - To be beautiful, & also usable to pavement engineers
  - Confidence in quality of data
  - ME Design & PMS Apps



